





Position, Location And Navigation (PLAN) Group Overview

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Who, What & Why?

- R&D and testing to improve positioning capabilities outdoor and indoor
- Strong history of working with government and industry on a variety of applications



- Key outcomes
 - Training of high quality personnel
 - Novel algorithms, processes and software
 - Technology transfer to industry through licenses, patents and contracts



Research Areas at a Glance

- GNSS software receiver development
 - Track and use new GNSS signals
 - IRNSS, Galileo, etc.
 - New architectures to improve performance
 - Interference and spoofing mitigation
- Integration with other sensors
 - Inertial navigation
 - Vehicle sensors (e.g., gyros, odometers, etc.)
 - Other ranging systems (e.g., UWB, DSSS, etc.)
- Pedestrian navigation
- Wide range of applications



More Information

http://plan.geomatics.ucalgary.ca

- All of our publications are posted online
 - Research → Projects
 - Research → Publications



